#### LINKING SENTINEL-1 LEVEL-1 DATA QUALITY WITH LEVEL-2 PERFORMANCE



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#### Outline



- Context
- Methodology
- Level-1 data quality
- Level-2 performance assessments for selected products
- Summary



#### **Geophysical information product accuracy assessment context**



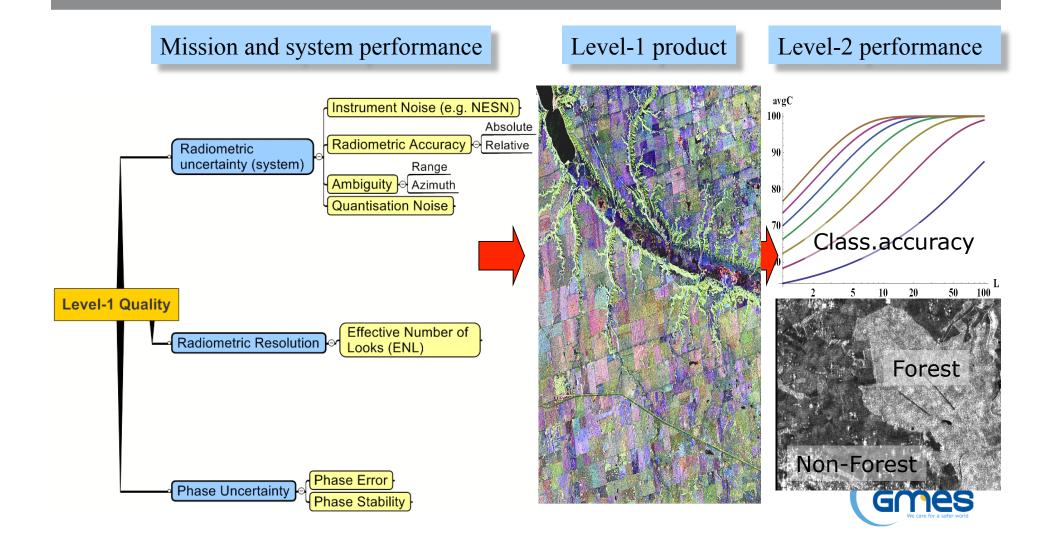
Time

- Support design of mission and trade-off studies
- Verification of technical choices of the mission and system
- Basis for definition of calibration and validation activities
- Preparation user community for new data stream and its capabilities ahead of launch
- Framework to support joint exploitation of ESA GMES missions and national contributing missions (e.g. TerraSAR-X, COSMO/ Skymed)
- Feedback to Agency in design of future SAR missions and integration of evolving user requirements



# Assessment framework for Level-2 performance assessment





### Sentinel-1 Level-1 data quality specifications



Parameter	Strip-Map	Interferometric	Extra Wide	Wave Mode
	Mode (SM)	Wide-Swath	Swath Mode	(WV)
		Mode (IW)	(EW)	
Polarisation	Dual	Dual	Dual	Single
	(HH+HV,	(HH+HV,	(HH+HV,	(HH, VV)
	VV+VH)	VV+VH)	VV+VH)	$(1111, \vee \vee)$
Access (Incidence	20° - 45°	25° (min.	20° (min.	23° + 36.5°(mid
angles)	20 - 43	incidence angle)	incidence angle)	incidence angle)
Azimuth Resolution	< 5 m	< 20 m	< 40 m	< 5 m
Ground Range	< 5 m	< 5 m	< 20 m	< 5 m
Resolution	< 5 m	< 5 m	< 20 m	< 5 m
Range Looks	Single	Single	Single	Single
Swath	> 80 km	> 250 km	> 400 km	Vignette 20 x 20 km
NESZ	-22 dB	-22 dB	-22 dB	-22 dB
Radiometric Stability	0.5 dB (3σ)	0.5 dB (3σ)	0.5 dB (3σ)	0.5 dB (3σ)
Radiometric Accuracy	1 dB (3σ)	1 dB (3σ)	1 dB (3σ)	1 dB (3σ)
Phase Error	5°	5°	5°	



# Origin of geophysical products and sources of uncertainty



Information Product (Level-2)	Origin of Product (Level-1)	Random & Systematic Uncertainties to be Considered (List not exhaustive)	
Soil Moisture Ocean Wind Speed	Absolute Value of Image Intensity	<ul> <li>Instrument Calibration, including Noise Bias and Non-linearity</li> <li>Radiometric Resolution, including Quantisation,</li> </ul>	
Ice Edge/Ice Map Oil Pollution at Sea Snow Cover Forest Map Land Cover Map	Image Intensity Contrast	<ul> <li>Noise and Speckle (Effective Number of Looks)</li> <li>Phase Errors</li> <li>Instrument Stability</li> <li>Atmospheric Effects</li> <li>Geometrical Effects (orbit position, pointing)</li> <li>Temporal De-correlation of Interferometric</li> </ul>	
Interferometric Products, e.g. Subsidence	Complex Image (Amplitude & Phase)	Image Pairs <ul> <li>Retrieval Uncertainties, including Retrieval</li> <li>Model Uncertainties and Validation Uncertainties</li> </ul>	imes

#### **Interferometry (1)**

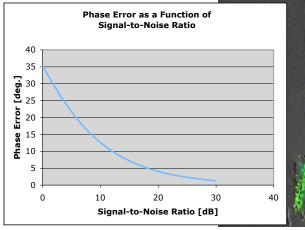


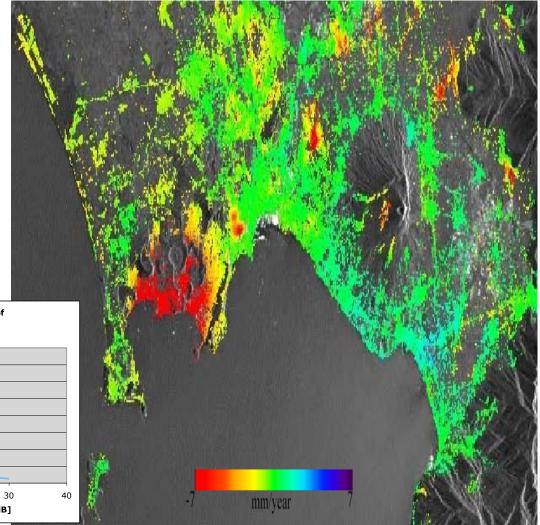
#### **Application context**

- Geo-Hazard Land Motion Services

#### Main mission parameters affecting performance

- Phase errors
- Quantisation noise
- Instrument noise





#### **Interferometry (2)**



100m2 Ground Resolution 832774 m Slant Range Methods for evaluation of geophysical 35.7 deg \_ **Mission Parameters** accuracy as a function of mission and 12 days Orbit repeat system parameters well established 0.70 Avg. target coherence Example reference scenario given on \_ 20 dB PS\_RCS right 0.98 Coherence 0.01m APS 2-way Target 5.14 deg APS\_std 129.80 deg Delay\_std Subsidence Rate Error (mm/year) -Permant Scatterer Coherence 700 Interferometric No PS (lobe) 1.33 mm/y 3 Performance -22 dB 2.5 NESZ 22 dB SNR Thermal 2 3.22 deg sphase thermal Thermal and 1.5 7.59 deg sphase\_target **Quantisation Noise** 16.99 dB SNR clutter 1 5.73 deg sphase clutter 0.5 3 deg sphase\_FDBAQ 0 30m 0 10 20 30 40 50 DEM std BAQ Phase Noise (deg) 30m Elevation Baseline std 24.24 deg topo std

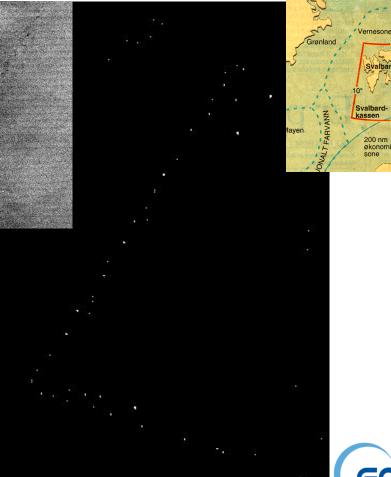
#### Ship detection (1)

#### Application context

- Security
- Oil-spill monitoring
- Fisheries/Transport

#### Main mission parameters impacting performance

- Swath Width
- Timeliness of data (< 1 hour)</li>
- Resolution
- Instrument Noise
- Performance models exist linking Level-1 data quality with ship detection performance





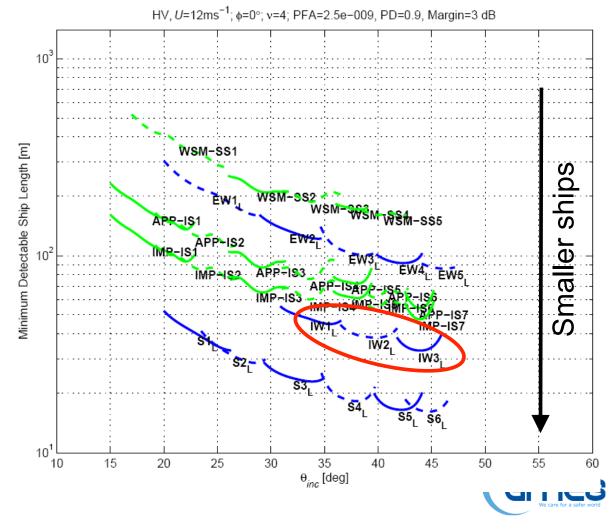
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#### Ship Detection (2)



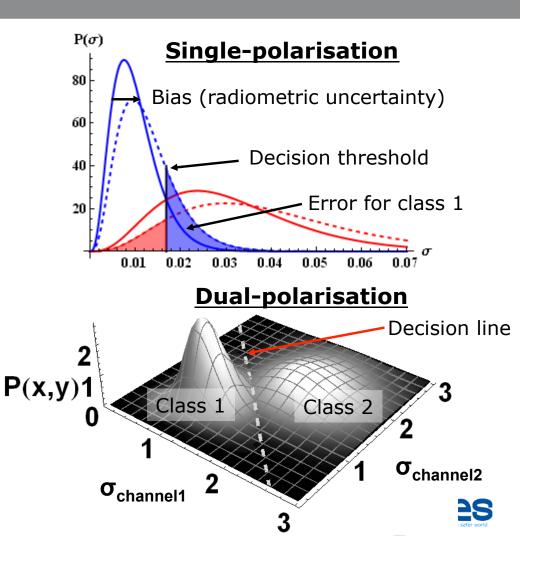
- Detection performance bette than existing C-band SAR satellites (ERS-2, Radarsat, ENVISAT)
- For the main IWS mode, ships with length > 40m can be detected with 90% accuracy
- For SM mode ships with length > 24m can be detected with 90% accuracy



#### **Classification error as a function of contrast**



- Methodology developed to explicitly calculate classification errors through integration of area/ volume of overlap
- Maximum likelihood criteria
- Classification error estimated as function of
  - radiometric contrast
  - level of bias (due to radiometric uncertainties)
- Applicable to wide variety of classification-based (thematic maps) applications



#### Ice monitoring (1)



#### **Application context**

- ice services
- manual interpretation of SAR images

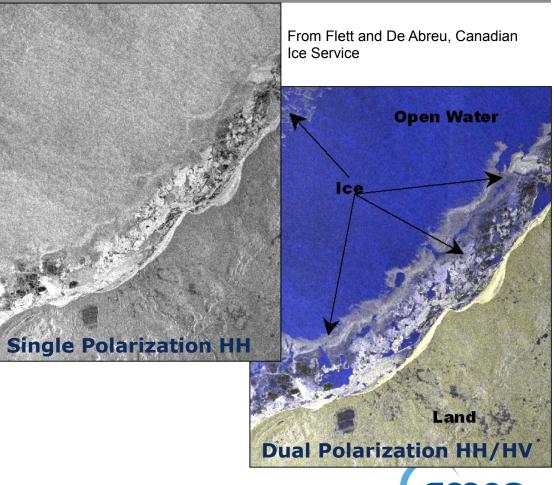
## Main mission parameters impacting performance

- Swath Width
- Timeliness of data
- Polarisation
- Instrument Noise

#### **Geophysical accuracy**

 combination of large swath and high resolution to provide needed coverage and input for interpretation

 dual-polarisation useful in detecting and mapping ice regimes

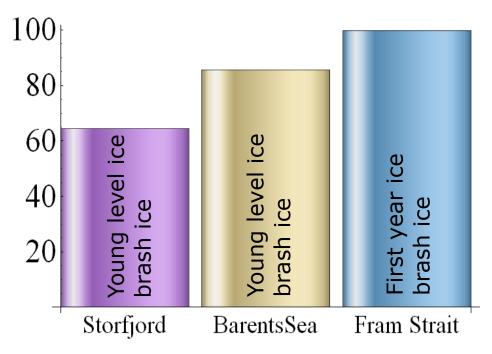




#### Ice monitoring (2)



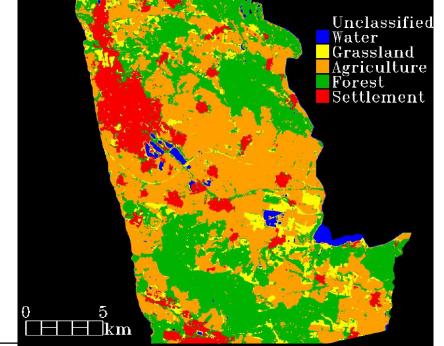
- Errors in ice classification estimated using previous methodology
  - S1 IWS Mode
  - Level-2 product scale = 20 x
     20m
  - 4 looks
  - 2 polarisations (VV+VH)
- Radiometric contrast between ice classes extracted from ESA IceSAR 2007 airborne campaign
- Main source of error: radiometric resolution





#### Land cover based on temporal signatures

- Robust land cover classification enabled through frequent revisit and multi-temporal metrics
  - Mean annual variation (MVA)
  - Min/Max/Mean backscatter
  - Texture
- High classification accuracies for basic land classes for sufficient temporal coverage (example with 8 acquisitions during growing season)



Maximum Likelihood VV & HV / 8 acq. dates	Water	Grassland	Cropland	Forest	Settlement	User accuracy
Water	97.88	1.217	0.27	0.22	0.85	89.35
Grassland	0.53	97.28	2.27	0.10	0.08	75.37
Cropland	1.24	1.503	95.99	0.64	16.82	97.73
Forest	0	0	1.15	98.92	0.085	99.21
Settlement	0.35	0	0.32	0.12	82.16	91.09
Prod. Accuracy	97.88	97.28	95.99	98.92	82.16	97.34

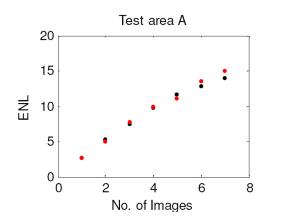


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#### **Radiometric Resolution**

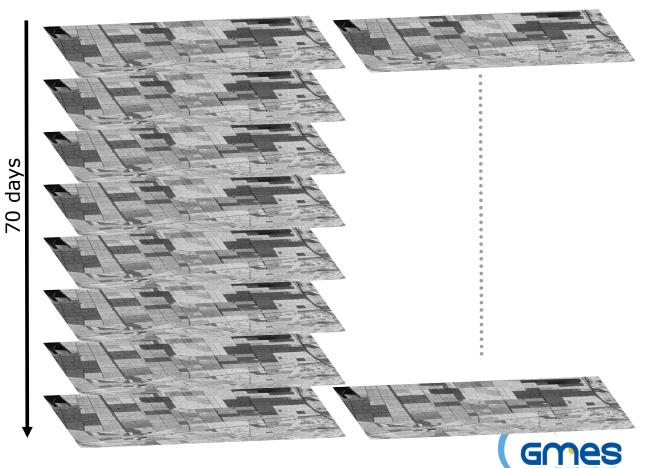


- Radiometric resolution is often a limiting factor on SAR-based classification performance
- Multi-temporal filtering exploiting image temporal stacks expected to significantly improve the radiometric resolution and classification performance



Sentinel-1

#### **ENVISAT ASAR**



#### **Forest/Non-Forest**

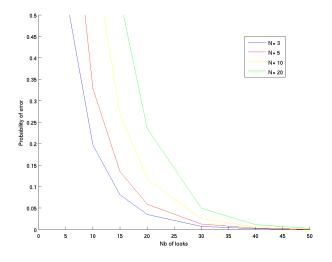


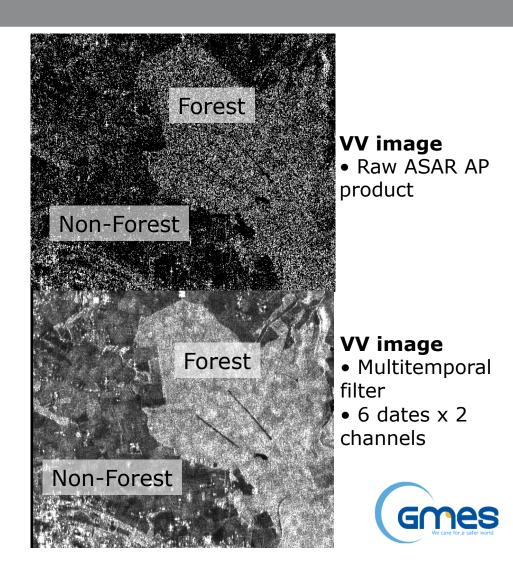
#### Context

 Forest/Non-forest mapping algorithms based on high temporal stability of forest with respect to other land cover classes

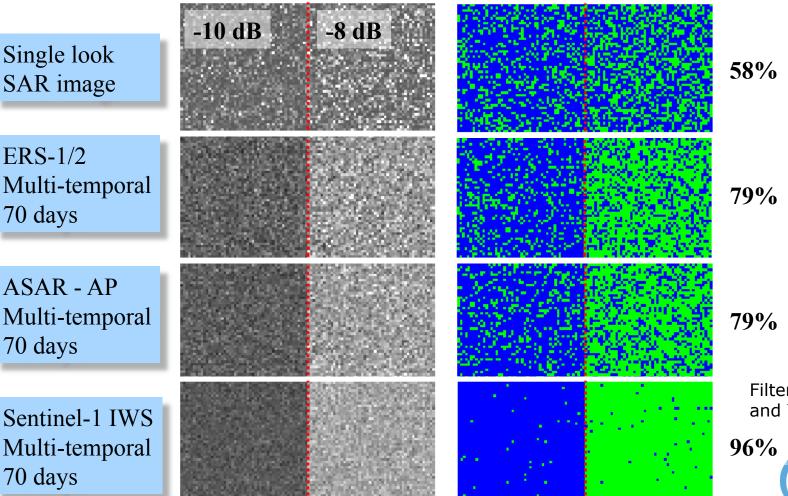
## Main mission parameters impacting accuracy

- Radiometric resolution





#### Synthetic classification performance potential based on ideal multi-temporal filtering



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Filter from Quegan and Yu (2001)



# Performance prediction for geophysical products



Gmes

S1 Level-2 Product	Resolution	Performance	Units
Subsidence Rate	5 x 20 m2	1.3	mm/year
Land Cover Classification (2 dB contrast )	100 x 100 m2	96	% correct classification
Forest Non-Forest Classification	30 x 30 m2	75	
Soil Moisture	100 x 100 m2	1.2	volume %
Flood Mapping	30 x 30 m2	79	% correct classification
Snow Cover Classification	30 x 30 m2	75	% correct classification
Ship Detection	5 x 20 m2	40	ship length (m) for 90% detection probability
Sea Surface Wind Speed	100 x 100 m2	0.8	m/s (1 sigma)
Sea Surface Currents	5 Hz	30	cm/s

#### **Summary**



- Sentinel-1 data products maintain the data quality of ESA's previous SAR missions (ERS-1/-2, ENVISAT ASAR)
  - Continuity in performance for geophysical products secured
- Evaluation of accuracy of geophysical products indicates improvements due to frequent revisit, coverage and dual-polarisation capabilities
  - System impact on Level-2 (and higher) evaluated based on Level-1 specifications
  - User requirements met or exceeded
  - Results documented in ESA Sentinel-1 Error Budget document
- Future work focus on development and standardisation of methodologies for accuracy assessment, product prototyping and (post-launch) verification of accuracy (e.g. through validation)

